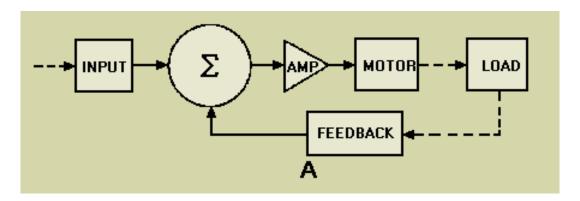


<u>Simple Servo System Block Diagram</u>

Figure 2-3, view A, is a block diagram of a closed-loop position servo.

Note the Greek letter Sigma (\square) meaning summation (AKA the Controller) surrounded by a circle.

Figure 2-3A. - Block diagram of a position servo.



This is the summation, or "sum point" where the input signal and the response signal (feedback) are summed to produce the error signal.

The driven motor will perform in accordance with the commanded velocity, and is continuously corrected via the feedback loop.